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Recent Developments in Discrete Torsion

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In this short article we briefly review some recent developments in understanding discrete torsion. Specifically, we give a short overview of the highlights of a group of recent papers which give the basic understanding of discrete torsion. Briefly, those papers observe that discrete torsion can be completely understand simply as the choice of action of the orbifold group on the B field. We summarize the main points of that work.

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1 Introduction

Historically discrete torsion has been a rather mysterious aspect of string theory. Discrete torsion was originally discovered [1] as an ambiguity in the choice of phases to assign to twisted sectors of string orbifold partition functions. Although other work has been done on the subject (see, for example, [2, 3, 4]), until recently no work has succeeded in giving any sort of genuinely deep understanding of discrete torsion. In fact, discrete torsion has sometimes been referred to has an inherently stringy degree of freedom, without any geometric analogue.

Recently, however, a purely mathematical understanding of discrete torsion was worked out [5, 6, 7, 8, 9]. In a nutshell,

Discrete torsion is the choice of orbifold group action on the B field.

More generally, in any theory containing fields with gauge invariances, to define an orbifold it does not suffice to only define the orbifold action on the base space. One must also specify the orbifold action on the fields. The choice of orbifold action on the fields is not unique, precisely because of the possibility of combining the orbifold group action with a gauge transformation.

For vector fields, these degrees of freedom lead to orbifold Wilson lines. For B fields, these degrees of freedom lead to discrete torsion.

Put another way, discrete torsion can be understood in purely mathematical terms, without any reference to string theory – it has nothing to do with string theory per se. At the end of the day, one can calculate twisted sector phases, orbifold group actions on D-branes, and so forth, so one can certainly work out physical consequences of discrete torsion. However, again, discrete torsion can ultimately be understood in purely mathematical terms.

Phrased differently, discrete torsion can no longer be considered to be mysterious – a perfectly sensible, and purely mathematical, description exists in [5, 6, 7, 8, 9].

In this article we shall give a brief overview of these developments in understanding discrete torsion [5, 6, 7, 8, 9].

In section 2 we discuss orbifold U(1) Wilson lines, which provide the prototype for our picture of discrete torsion. In section 3 we briefly discuss how the group $H^2(\Gamma, U(1))$ arises in describing orbifold group actions on B fields. In section 4 we discuss how the twisted sector phases of [1] can be derived. In section 5 we derive the projectivized orbifold group actions on D-brane worldvolumes used by M. Douglas in [3, 4] to describe discrete torsion for D-branes. In section 6 we outline how results of C. Vafa and E. Witten [2] on the interplay between discrete torsion and Calabi-Yau moduli can be understood in this framework. In section 7 we briefly review results on discrete torsion for perturbative heterotic strings. Finally, in

section 8 we briefly describe analogues of this story for other tensor field potentials.

2 Orbifold U(1) Wilson lines

Our description of discrete torsion in [5, 6, 7, 8, 9] has many very close parallels with orbifold U(1) Wilson lines. For example, just on a naive level, orbifold U(1) Wilson lines are counted by the group cohomology group¹ $H^1(\Gamma, U(1))$, and discrete torsion is associated with $H^2(\Gamma, U(1))$. Also, orbifold U(1) Wilson lines are technically far easier and less subtle to manipulate. For these reasons, in [5, 6, 7, 8, 9] we repeatedly stress the parallels with orbifold U(1) Wilson lines, and use orbifold U(1) Wilson lines as toy models for calculations involving B fields.

How does one describe the action of an orbifold group on a set of vector fields? One way is to specify how the orbifold group acts on the total space of the bundle; see for example [5] for an example of this approach. Another (equivalent) way (described in [7]) is to describe pullbacks of the gauge fields and transition functions in local coordinate patches. For example, we discuss in [7] how an orbifold group action on a set of vector fields defined by $(A^{\alpha}, g_{\alpha\beta})$,

$$A^{\alpha} - A^{\beta} = d \log g_{\alpha\beta}$$

can be written in the form

$$g^* A^{\alpha} = A^{\alpha} + d \log h_{\alpha}^g$$

$$g^* g_{\alpha\beta} = (g_{\alpha\beta}) (h_{\alpha}^g) (h_{\beta}^g)^{-1}$$

where g is an element of the orbifold group Γ , for an appropriate collection of Čech cochains $\{h_{\alpha}^g\}$.

How does the group $H^1(\Gamma, U(1))$ arise? Not directly. It can be shown that, in general, the set of orbifold group actions is a *set*, and does not even possess a group structure, so one cannot hope to understand orbifold group actions directly from the calculation of some (cohomology) group.

However, it can be shown that the set of orbifold group actions, although not itself a group, is acted upon by a group, namely $H^1(\Gamma, U(1))$. To be brief, given any one orbifold group action on a set of vector fields (principal U(1) bundle with connection), one can get to any other action by combining that action with a set of gauge transformations ϕ^g . These gauge transformations are required to respect the group law, meaning that

$$\phi^{gh} = \phi^h \cdot h^* \phi^g$$

¹Where Γ is the orbifold group.

and in order to preserve the gauge field, these gauge transformations must be constant. On a connected space, such a set of gauge transformations defines a homomorphism $\Gamma \to U(1)$, which is the same thing as an element of the group $H^1(\Gamma, U(1))$. In other words, although the set of orbifold group actions does not have a group structure, the difference between any two orbifold group actions is described by an element of the group $H^1(\Gamma, U(1))$.

Although the set of orbifold group actions does not in general have a group structure, in special cases (in fact, the special cases usually considered by physicists) one can impose a group structure. For example, if the bundle is topologically trivial, then there is a notion of a canonical trivial action (which only acts on the base, not the fiber). In this special case, one can describe any orbifold group action in terms of its difference from the canonical trivial action, and so (in this special case) one can speak of elements of $H^1(\Gamma, U(1))$ determining the orbifold group action. In general, however, one must be more careful.

Before going on to discuss B fields, we should make a few concluding remarks. First, our analysis of orbifold group actions on vector fields does not assume that Γ acts freely. Our analysis also does not assume that Γ is abelian. Finally, our analysis also does not assume that the bundle on which the gauge fields live is topologically trivial, although if it is not trivial, one must be careful to check that any orbifold group actions exist, which our analysis assumes.

3 $H^2(\Gamma, U(1))$

In this section we shall give a pedagogical outline of orbifold group actions on B fields. Our discussion here is not meant to be rigorous; however, rigorous versions do exist. In particular, reference [6] contains a completely rigorous description of orbifold group actions on B fields, and reference [7] contains a substantially simplified version.

In general terms, the same analysis holds for B fields as for vector fields. One can describe elements of the set of orbifold group actions on the B fields, and just as the difference between any two orbifold group actions on a U(1) gauge field is a set of gauge transformations ϕ^g , the difference between any two orbifold group transformations on a B field is a set of gauge transformations.

What is a gauge transformation of a B field? Locally, recall a gauge transformation of a B field looks like

$$B \mapsto B + d\Lambda$$

for Λ some one-form. We shall omit the details here (see instead [5, 6]), however the reader may correctly guess that globally, a gauge-transformation of a B field is determined by a principal U(1) bundle with connection – i.e., a set of U(1) gauge fields Λ .

In other words, to specify the difference between two orbifold group actions on a B field, we specify a set of principal U(1) bundles T^g with connection $\Lambda(g)$. Also, just as we had to restrict to constant gauge transformations of U(1) gauge fields in order to preserve the connection and count orbifold U(1) Wilson lines, here we must demand that the connection $\Lambda(g)$ on T^g be flat.

Now, there are two important subtleties in this description.

First, if Λ and Λ' are two connections that differ by a (bundle) gauge transformation, then they define the same gauge transformation of the B field. After all, the B field transforms as $B \mapsto B + d\Lambda$, so we can add any exact form to Λ without changing the gauge transformation of B. Globally, if $(T^g, \Lambda(g))$ and $(T'^g, \Lambda'(g))$ are two principal U(1) bundles with connection that differ by a connection-preserving bundle isomorphism, then they define the same gauge transformation of the B field.

Second, not any set $(T^g, \Lambda(g))$ will do – they must be well-behaved with respect to group composition. In other words, we must demand an analogue of the constraint

$$\phi^{g_1g_2} = \phi^{g_2} \cdot g_2^* \phi^{g_1} \tag{1}$$

that we imposed on the gauge-transformations relating orbifold group actions on U(1) gauge fields. Instead of U(1) valued functions ϕ^g , we now have bundles T^g . The correct analogue of equation (1) is that the bundle $T^h \otimes h^*T^g$ must be isomorphic to the bundle T^{gh} , and the same isomorphism must preserve the connection.

Let $\omega^{g,h}: T^h \otimes h^*T^g \to T^{gh}$ denote that connection-preserving isomorphism. Now, by composing the isomorphisms ω , we can construct two different isomorphisms between $T^{g_3} \otimes g_3^* (T^{g_2} \otimes g_2^*T^{g_1})$ and $T^{g_1g_2g_3}$; to be consistent, these two isomorphisms must be the same.

To summarize, we have stated that any two orbifold group actions on a set of B fields differ by a collection of principal U(1) bundles T^g with flat connection $\Lambda(g)$, together with connection-preserving bundle morphisms $\omega^{g_1,g_2}: T^{g_2} \otimes g_2^* T^{g_1} \to T^{g_1g_2}$, such that the following diagram commutes:

$$T^{g_3} \otimes g_3^* \left(T^{g_2} \otimes g_2^* T^{g_1} \right) \stackrel{\omega^{g_1, g_2}}{\longrightarrow} T^{g_3} \otimes g_3^* T^{g_1 g_2}$$

$$\downarrow^{\omega^{g_2, g_3}} \downarrow \qquad \qquad \downarrow^{\omega^{g_1 g_2, g_3}}$$

$$T^{g_2 g_3} \otimes (g_2 g_3)^* T^{g_1} \stackrel{\omega^{g_1, g_2 g_3}}{\longrightarrow} T^{g_1 g_2 g_3}$$

$$(2)$$

Also, we are free to replace any of the bundles T^g with isomorphic bundles. Let T'^g be another set of principal U(1) bundles with connection $\Lambda'(g)$, and $\kappa_g: T^g \to T'^g$ connection-preserving bundle isomorphisms, then we can replace the data given above with the collection $(T'^g, \Lambda'(g), \omega'^{g_1,g_2})$, where the ω' are given by

$$\omega'^{g_1,g_2} \equiv \kappa_{g_1g_2} \circ \omega^{g_1,g_2} \circ (\kappa_{g_2} \otimes g_2^* \kappa_{g_1})^{-1}$$
(3)



Figure 1: Lift of closed loop to covering space.

How does $H^2(\Gamma, U(1))$ arise in this description? Consider the special case that all the bundles T^g are topologically trivial, and the connections $\Lambda(g)$ are gauge-trivial. Without loss of generality, we can map each T^g to the canonical trivial bundle (whose transition functions are identically 1) and gauge-transform the connections $\Lambda(g)$ to be identically zero, not just gauge-trivial. Then the maps $\omega^{g,h}$ can be interpreted as gauge transformations (of the canonical trivial bundle), and furthermore constant gauge transformations (since they must preserve the connection, which is the same – zero – on both sides). Commutivity of diagram (2) then becomes the group 2-cocycle condition. So, in this choice of gauge, the maps $\omega^{g,h}$ are explicitly representatives of an element of $H^2(\Gamma, U(1))$.

In addition, there are residual gauge transformations – we can gauge-transform each of the bundles T^g by a constant gauge transformation, without making the connection $\Lambda(g)$ nonzero. From equation (3) we see that such gauge transformations of the bundles T^g change the $\omega^{g,h}$ by a group coboundary. So, B field gauge transformations of this form are classified by elements of $H^2(\Gamma, U(1))$.

In addition to these B field gauge transformations, which yield elements of $H^2(\Gamma, U(1))$, there can be additional B field gauge transformations, a fact which does not seem to have been noticed previously in the physics literature. These are discussed in more detail in [7].

4 Twisted sector phases

How do the twisted sector phases of [1] arise in this picture? In a nutshell, they arise because of the sigma model term $\int B$, and are precise analogues of Wilson loops.

Consider Wilson loop on a quotient space for a moment. Suppose on the covering space, the Wilson loop becomes an open line, with ends identified by the orbifold group action, as illustrated in figure (1). The Wilson loop on the quotient space is not merely

$$\exp\left(\int_x^{gx} A\right)$$

but also picks up a factor from a gauge transformation relating the gauge field A at x and qx. In other words, the Wilson loop on the quotient space is given by

$$\varphi \exp\left(\int_x^{gx} A\right)$$

for some φ .

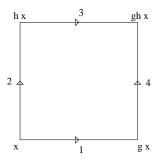


Figure 2: A twisted sector contribution to the one-loop partition function.

In [5, 7] we point out that the same considerations for Wilson surfaces $\exp(\int B)$ give rise to the twisted sector phases of [1].

For simplicity², assume B is topologically trivial. Consider a polygon on the covering space as shown in figure (2), describing a contribution to a one-loop twisted sector partition function. Naively, one might write the Wilson surface on the quotient space as merely $\exp(\int B)$, but just as for Wilson loops, this is wrong because it fails to take into account gauge transformations along the boundary.

As discussed earlier, a nontrivial orbifold group action on a (topologically trivial) B field is determined by a set of B field gauge transformations – that is, a set of principal U(1) bundles T^g with connection $\Lambda(g)$, and connecting maps $\omega^{g,h}$.

To take into account gauge transformations of the B field along the boundary, one naively would correct the factor $\exp(\int B)$ by adding a factor

$$\exp\left(\int_x^{hx} \Lambda(g) - \int_x^{gx} \Lambda(h)\right)$$

As discussed in [7], this is still not quite right, if for no other reason than it is not invariant under gauge transformations of the bundles T^g . To get a gauge-invariant result we must take into account the corners, which leads one to

$$\left(\omega_x^{g,h}\right)\left(\omega_x^{h,g}\right)^{-1} \exp\left(\int_x^{hx} \Lambda(g) - \int_x^{gx} \Lambda(h)\right)$$

Since this expression is gauge-invariant, we can evaluate it in any convenient gauge. For B field gauge transformations corresponding to elements of $H^2(\Gamma, U(1))$, a particularly convenient gauge is one in which all $\Lambda(g) \equiv 0$ and the $\omega^{g,h}$ are constant. Working in this

 $^{^2}$ So we can describe any orbifold group action in terms of a set of global gauge transformations distinguishing it from a canonical trivial action.

gauge, it is now clear that for such B field gauge transformations, the expression above is equal to the constant

$$\left(\omega^{g,h}\right)\left(\omega^{h,g}\right)^{-1}$$

which is precisely the phase factor given in [1]. Since this phase factor is constant, all contributions to the twisted sector partition function $Z_{(g,h)}$ are multiplied by the same factor, and so the effect is to multiply $Z_{(g,h)}$ by this phase.

In [7] we also derive the phase factors appearing in higher-loop string orbifold partition functions.

5 M. Douglas's orbifold actions and D-branes

In [3, 4], it was claimed that in terms of orbifold group actions on D-branes, discrete torsion is realized in terms of a projectivized action of the orbifold group.

In [7] we point out that this orbifold group action on D-brane worldvolumes is a natural consequence of the fact that the "bundle" on a D-brane is actually twisted by the B field. Specifically, since gauge transformations $B \mapsto B + d\Lambda$ induce $A \mapsto A + \Lambda$, the B field and the D-brane gauge fields are correlated. For a topologically trivial B field, for example, the transition functions for the "bundle" on the D-brane do not close as

$$g_{\alpha\beta} g_{\beta\gamma} g_{\gamma\alpha} = I$$

but rather close only up to a Čech cocycle $h_{\alpha\beta\gamma}$ defining the characteristic class of the B field:

$$g_{\alpha\beta} g_{\beta\gamma} g_{\gamma\alpha} = h_{\alpha\beta\gamma} I$$

Once one understands orbifold group actions on B fields, it is then straightforward to work out orbifold group actions on these "twisted bundles" appearing on D-brane worldvolumes, and one rapidly recovers the projectivized orbifold group action described in [3, 4].

6 Vafa-Witten

Reference [2] studied how discrete torsion affects Calabi-Yau moduli. Specifically, the authors of that paper studied deformations of toroidal orbifolds in which discrete torsion had been turned on. In general terms, they found that all nontrivial Kähler moduli were lifted, as well as many of the complex structure moduli.

In [7] we point out that these behaviors have a natural understanding in our picture. Briefly, turning on discrete torsion means that the quotient space has nontrivial Wilson surfaces $\exp(\int B)$. Just as turning on orbifold Wilson lines on quotients \mathbb{C}^2/Γ , for example, forces resolutions to have nonzero curvature supported on exceptional divisors, so nonzero Wilson surfaces forces one to need nonzero curvature H on any full resolution.

A blowup or small resolution of a toroidal orbifold tends to only introduce even-dimensional cycles, leaving no natural place for the B field curvature H to live. Therefore, one is naturally led to believe that nontrivial Kähler deformations are obstructed by the demands of consistency, and indeed this is what was observed in [2].

Complex structure resolutions, on the other hand, often introduce 3-cycles. So one could deform the complex structure of the toroidal orbifold, and naturally be led to a space with nonzero curvature H. However, nonzero H on a (Kähler) Calabi-Yau breaks supersymmetry, so any complex structure deformation that completely resolves the singularity would also be obstructed, as was noted in [2].

What deformations remain? One can still consistently deform the complex structure, but one cannot expect to completely resolve the space (at least, not to a Calabi-Yau). This is precisely what was found in [2].

A somewhat more detailed examination of how [2] can be naturally understood in the framework we have presented can be found in [7].

7 Perturbative heterotic strings

So far we have reviewed orbifold group actions on B fields whose curvature H is closed, in the sense that dH = 0. Unfortunately, the B fields of string theory do not always have this property. The most prominent exception is the B field of perturbative heterotic string theory. In this case, the curvature H is a (globally-defined) three-form such that $dH = \text{Tr } F \wedge F - \text{Tr } R \wedge R$, and so (except for the special case of the old-fashioned "standard embedding"), $dH \neq 0$ for the heterotic B field.

We examined orbifold group actions on the heterotic B field in detail in [9]. To be brief, we found that, for fixed orbifold group action on the gauge and tangent bundle, the difference between any two orbifold group actions on a heterotic B field was defined by the same data as for a type II B field. In other words, the difference between any two orbifold group actions on a heterotic B field is defined by data (T^g, ω^{g_1,g_2}) , where the T^g are principal U(1)-bundles with connection (one for each $g \in \Gamma$), and the ω^{g_1,g_2} are connection-preserving bundle isomorphisms, subject to the same equivalence relations as before.

Thus, for heterotic B fields as well as type II B fields, we find the same occurrence of

 $H^2(\Gamma, U(1))$, as well as twisted-sector phases.

8 Analogues for C fields

We have repeatedly stressed that orbifold group actions on any field with gauge invariances are not unique, because one can combine the orbifold group action with a gauge transformation. For vector fields, this ambiguity is known as "orbifold Wilson lines," and we have explained in [5, 6, 7] how for B fields this ambiguity is discrete torsion.

String theory has other fields beyond vector fields and B fields; what degrees of freedom does one find in defining orbifold group actions on these other fields?

In reference [8] we explore this matter for the M-theory three-form. In order to get concrete results, we make the slightly simplistic assumption that the C field can be understood as a connection on a 2-gerbe. When we repeat the calculations of [7], we find that part of the difference between orbifold group actions is classified by $H^3(\Gamma, U(1))$, though there can be additional orbifold group actions also.

One might ask what the analogue of the twisted sector phases of [1] are for membranes. The answer is as follows [7]: given a "twisted sector" on T^3 defined by a commuting triple (g_1, g_2, g_3) , under an orbifold group action on a trivial C field determined by an element of $H^3(\Gamma, U(1))$, the factor

$$\exp\left(\int C\right)$$

picks up a factor of

$$(\omega^{g_1,g_2,g_3})\ (\omega^{g_2,g_1,g_3})^{-1}\ (\omega^{g_3,g_2,g_1})^{-1}\ (\omega^{g_3,g_1,g_2})\ (\omega^{g_2,g_3,g_1})\ (\omega^{g_1,g_3,g_2})^{-1}$$

from gauge transformations at the boundaries, where ω^{g_1,g_2,g_3} is a group 3-cocycle. This expression is invariant under changing the cocycle by a coboundary (as it must be, to associate a well-defined phase to an element of $H^3(\Gamma, U(1))$), and is also invariant under the natural $SL(3, \mathbf{Z})$ action on T^3 .

Admittedly the analysis in [8] is slightly naive – it is really just an analysis of orbifold group actions on 2-gerbes, and does not take much physics into account. For example, it ignores the flux-quantization-shifting effect described in [10], which almost certainly will have an effect here.

However, although the analysis is naive, it does highlight the fact that one does expect an analogue of discrete torsion for the M-theory C field, and gives a first rough idea of what those degrees of freedom should look like.

9 Conclusions

In this short article we have given a brief general overview of the basic understanding of discrete torsion described in [5, 6, 7, 8]. Those references explain that discrete torsion is simply the choice of orbifold group action on the B field; all the basic properties of discrete torsion, from its appearance as twisted sector phases [1] to M. Douglas's description of discrete torsion for D-branes [3, 4] follows from this description.

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